An overview of the Itô formula

Diogo Pinheiro

CEMAPRE - ISEG - UTL dpinheiro@iseg.utl.pt

December 2, 2009

・ロト ・四ト ・ヨト ・ヨト

Definition

Denote by $\{\mathcal{F}_t\}_{t\geq 0}$ the filtration generated by the one-dimensional Brownian motion B_t and by \mathcal{B} the Borel σ -algebra on $[0,\infty)$. Let $\mathcal{V} = \mathcal{V}(S,T)$ be the class of functions $f:[0,\infty) \times \Omega \to \mathbb{R}$ such that (i) $(t,\omega) \to f(t,\omega)$ is $\mathcal{B} \times \mathcal{F}$ -measurable. (ii) $f(t,\omega)$ is \mathcal{F}_t -adapted. (iii) $E\left[\int_S^T (f(t,\omega))^2 \mathrm{d}t\right] < \infty$.

 We have already defined the Itô integral for functions f ∈ V (as well as for larger classes of functions) and studied some of its properties.

イロト イポト イヨト イヨト

Definition (Elementary function)

A function $\phi \in \mathcal{V}(S, T)$ is called *elementary* if it has the form

$$\phi(t,\omega) = \sum_j e_j(\omega) I_{[t_j,t_{j+1})}(t) \; ,$$

where the points t_j define a partition of the interval [S, T]. We have been using a partition defined by the points

$$t_j = t_j^{(n)} = \begin{cases} j2^{-n} & \text{if } S \le j2^{-n} \le T \\ S & \text{if } j2^{-n} < S \\ T & \text{if } j2^{-n} > T \end{cases}$$

• Note that since $\phi \in \mathcal{V}$ then $e_j(\omega)$ must be \mathcal{F}_{t_i} -measurable.

• For elementary functions $\phi(t,\omega)$ we define the stochastic integral as

$$\int_{S}^{T} \phi(t,\omega) \mathrm{d}B_{t}(\omega) = \sum_{j\geq 0} e_{j}(\omega) [B_{t_{j+1}} - B_{t_{j}}](\omega) ,$$

Definition (The Itô integral)

Let $f \in \mathcal{V}(S, T)$. Then the *Itô integral* of f (from S to T) is defined by

$$\int_{S}^{T} f(t,\omega) dB_{t}(\omega) = \lim_{n \to \infty} \int_{S}^{T} \phi_{n}(t,\omega) dB_{t}(\omega) \quad \text{limit in } L^{2}(P) , \qquad (1)$$

where $\{\phi_n\}$ is a sequence of elementary functions such that

$$\mathsf{E}\left[\int_{\mathcal{S}}^{\mathcal{T}} (f(t,\omega) - \phi_n(t,\omega))^2 \mathrm{d}t\right] \to 0 \quad \text{as } n \to \infty , \qquad (2)$$

where the limit in (1) exists and does not depend on the choice of $\{\phi_n\}$, as long as (2) holds.

・ロト ・ 日 ・ ・ ヨ ・ ・ ヨ ・

- Properties of the Itô integral:
 - Itô isometry:

$$E\left[\left(\int_{S}^{T} f(t,\omega) \mathrm{d}B_{t}(\omega)\right)^{2}\right] = E\left[\int_{S}^{T} \left(f(t,\omega)\right)^{2} \mathrm{d}t\right] \quad \text{for all } f \in \mathcal{V}(S,T)$$

Linearity

•
$$E\left[\int_{S}^{T} f \mathrm{d}B_{t}\right] = 0$$

- $\int_{S}^{T} f dB_t$ is \mathcal{F}_T -measurable
- Existence of a continuous version
- The martingale property

< ロ > < 同 > < 回 > < 回 >

Motivation for the Itô formula

Let us recall the computation of the Itô integral $\int_0^t B_s dB_s = \frac{1}{2}B_t^2 - \frac{1}{2}t$.

Example

Assume $B_0 = 0$. We consider the sequence of elementary functions

$$\phi_n(t,\omega) = \sum_j B_j(\omega) I_{[t_j,t_{j+1}]}(t),$$

where $B_j = B_{t_j}$. Then

$$E\left[\int_{0}^{t} (\phi_{n} - B_{s})^{2} ds\right] = E\left[\sum_{j} \int_{t_{j}}^{t_{j+1}} (B_{j} - B_{s})^{2} ds\right]$$
$$= \sum_{j} \int_{t_{j}}^{t_{j+1}} (s - t_{j}) ds$$
$$= \sum_{j} \frac{1}{2} (t_{j+1} - t_{j})^{2} \to 0 \text{ as } \Delta t_{j} \to 0.$$

<ロ> (日) (日) (日) (日) (日)

Motivation for the Itô formula

Example

Thus,

$$\int_0^t B_s \mathrm{d}B_s = \lim_{\Delta t_j \to 0} \int_0^t \phi_n \mathrm{d}B_s = \lim_{\Delta t_j \to 0} \sum_j B_j \Delta B_j \; .$$

We now note that

$$\Delta(B_j^2) = B_{j+1}^2 - B_j^2 = (B_{j+1} - B_j)^2 + 2B_j(B_{j+1} - B_j) = (\Delta B_j)^2 + 2B_j\Delta B_j \; ,$$

and therefore

$$B_t^2 = \sum_j \Delta(B_j^2) = \sum_j (\Delta B_j)^2 + 2 \sum_j B_j \Delta B_j ,$$

that is

$$\sum_j B_j \Delta B_j = rac{1}{2} B_t^2 - rac{1}{2} \sum_j (\Delta B_j)^2 \; .$$

Noting that $\sum_j (\Delta B_j)^2 \to t$ in $L^2(P)$ as $\Delta t_j \to 0$, we obtain the result.

Motivation for the Itô formula

Example

$$\int_0^t B_s \mathrm{d}B_s = \frac{1}{2}B_t^2 - \frac{1}{2}t \; .$$

- This example illustrates that the definition of Itô integral is not very useful when we try to evaluate a given integral.
 - We face the same kind of problems posed by the computation of ordinary Riemann integrals using its definition.
 - * But to compute Riemann integrals we do not usually use its definition, but rather a combination of the fundamental theorem of calculus and the chain rule.
 - However, in the context of stochastic calculus, we have no differentiation theory, only integration theory.
 - Nevertheless, it is possible to establish an Itô integral version of the chain rule, called the Itô formula.
 - > The Itô formula turns out to be extremely useful for evaluating Itô integrals.

< ロ > < 同 > < 回 > < 回 >

ltô processes

• From the identity

$$\int_0^t B_s \mathrm{d}B_s = \frac{1}{2}B_t^2 - \frac{1}{2}t \; .$$

we get

$$rac{1}{2}B_t^2 = rac{1}{2}t + \int_0^t B_s \mathrm{d}B_s \; .$$

• Note that the image of the Itô integral $B_t = \int_0^t dB_s$ by the map $g(x) = \frac{1}{2}x^2$ is not again an Itô integral of the form

$$\int_0^t f(s,\omega) \mathrm{d}B_s(\omega)$$

but rather a combination of two integrals.

$$\frac{1}{2}B_t^2 = \int_0^t \frac{1}{2}\mathrm{d}s + \int_0^t B_s \mathrm{d}B_s \ .$$

 If we introduce Itô processes (also called stochastic integrals) as sums of a Itô integral and a Riemann integral then this family of integrals is stable under smooth maps.

ltô processes

 Before giving a precise definition of Itô processes, let us recall the definition of the class of functions W_H.

Definition (Class of functions $\mathcal{W}_{\mathcal{H}}(S, T)$)

We denote by $W_{\mathcal{H}}(S, T)$ the class of functions $f : [0, \infty) \times \Omega \to \mathbb{R}$ satisfying the following three conditions

(i) $(t, \omega) \rightarrow f(t, \omega)$ is $\mathcal{B} \times \mathcal{F}$ -measurable.

(ii)' There exists an increasing family of σ -algebras \mathcal{H}_t , $t \geq 0$ such that:

- a) B_t is a martingale with respect to \mathcal{H}_t
- b) $f(t, \omega)$ is \mathcal{H}_t -adapted.

(iii)'
$$P\left[\int_{S}^{T} f(s,\omega)^{2} \mathrm{d}s < \infty\right] = 1.$$

We denote by $\mathcal{W}_{\mathcal{H}}$ the set defined by $\mathcal{W}_{\mathcal{H}} = \bigcap_{T>0} \mathcal{W}_{\mathcal{H}}(0, T)$. We denote by $\mathcal{W}_{\mathcal{H}}^{m \times n}(S, T)$ the set of $m \times n$ matrices with entries on $\mathcal{W}_{\mathcal{H}}(S, T)$.

ltô processes

Definition (1-dimensional Itô process)

Let B_t be 1-dimensional Brownian motion on a probability space (Ω, \mathcal{F}, P) . A (1-dimensional) Itô process is a stochastic process X_t on (Ω, \mathcal{F}, P) of the form

$$X_t = X_0 + \int_0^t u(s,\omega) \mathrm{d}s + \int_0^t v(s,\omega) \mathrm{d}B_s ,$$

where $v \in \mathcal{W}_{\mathcal{H}}$ so that

$$P\left[\int_0^t v(s,\omega)^2 \mathrm{d} s < \infty ext{ for all } t \geq 0
ight] = 1$$

and u is \mathcal{H}_t -adapted and such that

$$P\left[\int_0^t |u(s,\omega)| \mathrm{d} s < \infty ext{ for all } t \geq 0
ight] = 1 \;.$$

・ロッ ・ 一 ・ ・ ・ ・

Itô processes

• An Itô process X_t of the form

$$X_t = X_0 + \int_0^t u(s,\omega) \mathrm{d}s + \int_0^t v(s,\omega) \mathrm{d}B_s \; ,$$

can be written in the shorter differential form

$$\mathrm{d}X_t = u\mathrm{d}t + v\mathrm{d}B_t \; .$$

Recalling the example above, we note that the Itô process

$$\frac{1}{2}B_t^2 = \int_0^t \frac{1}{2}\mathrm{d}s + \int_0^t B_s \mathrm{d}B_s \ .$$

can be rewritten as

$$\mathrm{d}\left(\frac{1}{2}B_t^2\right) = \frac{1}{2}\mathrm{d}t + B_t\mathrm{d}B_t \;.$$

(日)

Theorem (The 1-dimensional Itô formula) Let X_t be an Itô process given by

 $\mathrm{d}X_t = u\mathrm{d}t + v\mathrm{d}B_t$

and let $g(t,x)\in C^2([0,\infty) imes \mathbb{R}).$ Then

 $Y_t = g(t, X_t)$

is again an Itô process, and

$$\mathrm{d}Y_t = \frac{\partial g}{\partial t}(t, X_t)\mathrm{d}t + \frac{\partial g}{\partial x}(t, X_t)\mathrm{d}X_t + \frac{1}{2}\frac{\partial^2 g}{\partial x^2}(t, X_t)(\mathrm{d}X_t)^2 ,$$

where $(dX_t)^2 = (dX_t).(dX_t)$ is computed according to the "multiplication table"

$$\mathrm{d}t.\mathrm{d}t = \mathrm{d}t.\mathrm{d}B_t = \mathrm{d}B_t.\mathrm{d}t = 0$$
, $\mathrm{d}B_t.\mathrm{d}B_t = \mathrm{d}t$.

・ロト ・ 同ト ・ ヨト ・ ヨ

Proof.

Observe that if we substitute

$$\mathrm{d}X_t = u\mathrm{d}t + v\mathrm{d}B_t$$

in

$$\mathrm{d}Y_t = \frac{\partial g}{\partial t}(t, X_t)\mathrm{d}t + \frac{\partial g}{\partial x}(t, X_t)\mathrm{d}X_t + \frac{1}{2}\frac{\partial^2 g}{\partial x^2}(t, X_t)(\mathrm{d}X_t)^2$$

and use the "multiplication table"

$$\mathrm{d}t.\mathrm{d}t = \mathrm{d}t.\mathrm{d}B_t = \mathrm{d}B_t.\mathrm{d}t = 0 \ , \qquad \mathrm{d}B_t.\mathrm{d}B_t = \mathrm{d}t \ .$$

we get the equivalent expression

$$\begin{split} g(t,X_t) &= g(0,X_0) + \int_0^t \frac{\partial g}{\partial t}(s,X_s) + u \frac{\partial g}{\partial x}(s,X_s) + \frac{1}{2} v^2 \frac{\partial^2 g}{\partial x^2}(s,X_s) \mathrm{d}s \\ &+ \int_0^t v \frac{\partial g}{\partial x}(s,X_s) \mathrm{d}B_s \;, \end{split}$$

which is still an Itô process.

Diogo Pinheiro (CEMAPRE)

Proof.

We can assume that:

- 1) the functions g, $\frac{\partial g}{\partial t}$, $\frac{\partial g}{\partial x}$ and $\frac{\partial^2 g}{\partial x^2}$ are bounded.
 - If this is the case, we obtain the general case by approximating by C^2 functions g_n such that g_n , $\frac{\partial g_n}{\partial t}$, $\frac{\partial g_n}{\partial x}$ and $\frac{\partial^2 g_n}{\partial x^2}$ are bounded for each n and converge uniformly on compact subsets of $[0, +\infty) \times \mathbb{R}$ to g, $\frac{\partial g}{\partial t}$, $\frac{\partial g}{\partial x}$ and $\frac{\partial^2 g}{\partial x^2}$, respectively.

2)
$$u(t,\omega)$$
 and $v(t,\omega)$ are elementary functions.

Because if $f \in W_H$ then for all t there exist step functions $f_n \in W_H$ such that

$$\int_0^t |f - f_n| \mathrm{d}s \to 0 \qquad \text{(in probability)}$$

and, therefore,

$$\int_0^t f(s,\omega) \mathrm{d} B_s(\omega) = \lim_{n \to \infty} \int_0^t f_n(s,\omega) \mathrm{d} B_s(\omega) \qquad (\text{in probability}) \ .$$

Proof.

Using Taylor's theorem we get

$$\begin{split} g(t,X_t) &= g(0,X_0) + \sum_j \Delta g(t_j,X_j) \\ &= g(0,X_0) + \sum_j \frac{\partial g}{\partial t} \Delta t_j + \sum_j \frac{\partial g}{\partial x} \Delta X_j \\ &+ \frac{1}{2} \sum_j \frac{\partial^2 g}{\partial t^2} (\Delta t_j)^2 + \frac{1}{2} \sum_j \frac{\partial^2 g}{\partial t \partial x} \Delta t_j \Delta X_j + \frac{1}{2} \sum_j \frac{\partial^2 g}{\partial x^2} (\Delta X_j)^2 \\ &+ \sum_j R_j , \end{split}$$

where

• the functions g, $\frac{\partial g}{\partial t}$, $\frac{\partial g}{\partial x}$, $\frac{\partial^2 g}{\partial t^2}$, $\frac{\partial^2 g}{\partial t \partial x}$ and $\frac{\partial^2 g}{\partial x^2}$ are all evaluated at (t_j, X_{t_j}) . • $\Delta t_j = t_{j+1} - t_j$, $\Delta X_j = X_{j+1} - X_j$, $\Delta g(t_j, X_j) = g(t_{j+1}, X_{j+1}) - g(t_j, X_j)$. • $R_j = o(|\Delta t_j|^2 + |\Delta X_j|^2)$ for all j.

Proof.

If $\Delta t_j \rightarrow 0$ then

$$\sum_{j} \frac{\partial g}{\partial t} \Delta t_{j} = \sum_{j} \frac{\partial g}{\partial t} (t_{j}, X_{t_{j}}) \Delta t_{j} \rightarrow \int_{0}^{t} \frac{\partial g}{\partial s} (s, X_{s}) \mathrm{d}s$$

and

$$\sum_{j} \frac{\partial g}{\partial x} \Delta X_{j} = \sum_{j} \frac{\partial g}{\partial x} (t_{j}, X_{t_{j}}) \Delta X_{j} \rightarrow \int_{0}^{t} \frac{\partial g}{\partial x} (s, X_{s}) \mathrm{d}X_{s} \ .$$

Since u and v are elementary, we get

$$\begin{split} \sum_{j} \frac{\partial^2 g}{\partial x^2} (\Delta X_j)^2 &= \sum_{j} \frac{\partial^2 g}{\partial x^2} (t_j, X_{t_j}) u_j^2 (\Delta t_j)^2 + \sum_{j} \frac{\partial^2 g}{\partial x^2} (t_j, X_{t_j}) u_j v_j \Delta t_j \Delta B_j \\ &+ \sum_{j} \frac{\partial^2 g}{\partial x^2} (t_j, X_{t_j}) v_j^2 (\Delta B_j)^2 \;. \end{split}$$

where $u_j = u_j(t_j, \omega)$ and $v_j = v_j(t_j, \omega)$.

Proof.

The first two terms in the previous equality tend to zero as $\Delta t_j \rightarrow 0$. To see this, note that, for instance

$$E\left[\left(\sum_{j}\frac{\partial^{2}g}{\partial x^{2}}u_{j}v_{j}\Delta t_{j}\Delta B_{j}\right)^{2}\right]=\sum_{j}E\left[\left(\frac{\partial^{2}g}{\partial x^{2}}u_{j}v_{j}\right)^{2}\right](\Delta t_{j})^{3}\rightarrow0\text{ as }\Delta t_{j}\rightarrow0.$$

In a similar fashion the terms

$$\frac{1}{2}\sum_{j}\frac{\partial^2 g}{\partial t^2}(\Delta t_j)^2$$

and

$$\frac{1}{2}\sum_{j}\frac{\partial^2 g}{\partial t\partial x}\Delta t_j\Delta X_j$$

also tend to zero as $\Delta t_j \rightarrow 0$.

Proof.

It remains to be proved that

$$\sum_{j} \frac{\partial^2 g}{\partial x^2}(t_j, X_{t_j}) v_j^2 (\Delta B_j)^2 \to \int_0^t v^2 \frac{\partial^2 g}{\partial x^2} \mathrm{d}s \qquad \text{in } L^2(P) \text{ as } \Delta t_j \to 0.$$

To prove it, we introduce the notation $a(t) = v^2(t, \omega) \frac{\partial^2 g}{\partial x^2}(t, X_t)$, $a_j = a(t_j)$ and consider

$$E\left[\left(\sum_{j}a_{j}(\Delta B_{j})^{2}-\sum_{j}a_{j}\Delta t_{j}\right)^{2}\right]=\sum_{i,j}E\left[a_{i}a_{j}((\Delta B_{i})^{2}-\Delta t_{i})((\Delta B_{j})^{2}-\Delta t_{j})\right]$$

If i < j then the terms $a_i a_j ((\Delta B_i)^2 - \Delta t_i)$ and $((\Delta B_j)^2 - \Delta t_j)$ are independent and so the corresponding terms in the sum vanish in this case and similarly for i > j.

Proof.

Therefore, we are left with

$$\sum_{j} E\left[a_{j}^{2}((\Delta B_{j})^{2} - \Delta t_{j})^{2}\right] = \sum_{j} E\left[a_{j}^{2}\right] E\left[(\Delta B_{j})^{4} - 2(\Delta B_{j})^{2}(\Delta t_{j}) + (\Delta t_{j})^{2}\right]$$
$$= \sum_{j} E\left[a_{j}^{2}\right] E\left[3(\Delta t_{j})^{2} - 2(\Delta t_{j})^{2} + (\Delta t_{j})^{2}\right]$$
$$= 2\sum_{j} E\left[a_{j}^{2}\right] (\Delta t_{j})^{2} \quad \text{as } \Delta t_{j} \to 0.$$

Therefore, we have established that

$$\sum_j a_j (\Delta B_j)^2 o \int_0^t a(s) \mathrm{d}s \qquad ext{in } L^2(P) ext{ as } \Delta t_j o 0,$$

which is also often expressed as $(dB_t)^2 = dt$ The arguments above also prove that $\sum_j R_j \to 0$ as $\Delta t_j \to 0$, which completes the proof of the Itô formula.

- Note that:
 - it is enough that g(t, x) is C² on [0,∞) × U, if U ⊂ ℝ is an open set such that X_t(ω) ∈ U for all t ≥ 0 and ω ∈ Ω.
 - it is enough to assume that g(t, x) is C^1 in t and C^2 in x.

< □ > < 同 > < 回 >

Example

To compute the integral

$$\int_0^t B_s \mathrm{d}B_s$$

one can choose $X_t = B_t$ and $g(t, x) = \frac{1}{2}x^2$ and apply Itô formula to

$$Y_t = g(t, B_t) = \frac{1}{2}B_t^2$$

to get

$$dY_t = g(t, B_t) = \frac{\partial g}{\partial t}(t, B_t)dt + \frac{\partial g}{\partial x}(t, B_t)dB_t + \frac{1}{2}\frac{\partial^2 g}{\partial x^2}(t, B_t)(dB_t)^2$$
$$= B_t dB_t + \frac{1}{2}dt$$
$$= \frac{1}{2}dt + B_t dB_t .$$

Example		
Therefore,	(1) 1	
	$\mathrm{d}\left(\frac{1}{2}B_t^2\right) = \frac{1}{2}\mathrm{d}t + B_t\mathrm{d}B_t$	
and thus	$1 + \ell^t$	
	$rac{1}{2}B_t^2 = rac{t}{2} + \int_0^t B_s \mathrm{d}B_s$	
or		
	$\int_0^t B_s \mathrm{d}B_s = \frac{1}{2}B_t^2 - \frac{t}{2}$	

-

э

・ロト ・日 ・ ・ ヨ ・ ・

Example

Let us assume that $f : \mathbb{R} \to \mathbb{R}$ is C^1 . To compute the integral

$$\int_0^t f(s) \mathrm{d}B_s \; .$$

we can use some real variable calculus intuition, i.e. it seem reasonable that a term of the form $f(t)B_t$ should appear when computing the integral above. Therefore, we choose $X_t = B_t$ and g(t, x) = f(t)x and apply Itô formula to

$$Y_t = g(t, B_t) = f(t)B_t$$

to get

$$dY_t = g(t, B_t) = \frac{\partial g}{\partial t}(t, B_t)dt + \frac{\partial g}{\partial x}(t, B_t)dB_t + \frac{1}{2}\frac{\partial^2 g}{\partial x^2}(t, B_t)(dB_t)^2$$
$$= f'(t)B_tdt + f(t)dB_t .$$

Example

Therefore,

$$\mathrm{d}\left(f(t)B_t\right) = f'(t)B_t\mathrm{d}t + f(t)\mathrm{d}B_t$$

and thus

$$f(t)B_t = \int_0^t f'(s)B_s \mathrm{d}s + \int_0^t f(s)\mathrm{d}B_s$$

or

$$\int_0^t f(s) \mathrm{d}B_s = f(t)B_t - \int_0^t f'(s)B_s \mathrm{d}s$$

・ロン ・四マ ・ヨン ・田

• We can extend the previous reasoning to obtain the following analogue of the integration by parts formula.

Theorem (Integration by parts)

Suppose the $f(s, \omega) = f(s)$ only depends on s and that f is continuous and of bounded variation in [0, t]. Then

$$\int_0^t f(s) \mathrm{d}B_s = f(t)B_t - \int_0^t B_s \mathrm{d}f(s) \; .$$

(日)

Definition (Multi-dimensional Itô process)

Let $B(t, \omega) = (B_1(t, \omega), ..., B_m(t, \omega))$ denote *m*-dimensional Brownian motion. Assume that for each $i \in \{1, ..., n\}$ and each $j \in \{1, ..., m\}$ we have that the processes $u_i = u_i(t, \omega)$ and $v_{ij} = v_{ij}(t, \omega)$ are such that $v_{ij} \in W_H$ and

$$P\left[\int_0^t v_{ij}(s,\omega)^2 \mathrm{d}s < \infty ext{ for all } t \geq 0
ight] = 1,$$

and u_i is \mathcal{H}_t -adapted and such that

$${\sf P}\left[\int_0^t |u_i(s,\omega)| \mathrm{d} s < \infty ext{ for all } t \geq 0
ight] = 1 \;.$$

A (Multi-dimensional) Itô process is a stochastic process of the form

$$\begin{cases} dX_1 = u_1 dt + v_{11} dB_1 + \cdots + v_{1m} dB_m \\ \vdots & \vdots \\ dX_n = u_n dt + v_{n1} dB_1 + \cdots + v_{nm} dB_m \end{cases}$$

 Note that one could also represent a Multi-dimensional Itô process on matrix form

$$\mathrm{d}X = u\mathrm{d}t + v\mathrm{d}B \; ,$$

where

$$X(t) = \begin{pmatrix} X_1(t) \\ \vdots \\ X_n(t) \end{pmatrix} , \quad u = \begin{pmatrix} u_1 \\ \vdots \\ u_n \end{pmatrix}$$
$$v = \begin{pmatrix} v_{11} \cdots v_{1m} \\ \vdots & \vdots \\ v_{n1} \cdots v_{nm} \end{pmatrix} , \quad dB(t) = \begin{pmatrix} dB_1(t) \\ \vdots \\ dB_m(t) \end{pmatrix}$$

メロト メポト メヨト メヨ

.

Theorem (The Multi-dimensional Itô formula)

Let

$$\mathrm{d}X(t) = u\mathrm{d}t + v\mathrm{d}B(t)$$

be an n-dimensional Itô process and let $g(t, x) = (g_1(t, x), ..., g_p(t, x))$ be a C^2 map from $[0, \infty) \times \mathbb{R}^n$ into \mathbb{R}^p .

Then the process

$$Y(t) = g(t, X(t))$$

is again an Itô process and its kth component Y_k is given by

$$\mathrm{d}Y_k = \frac{\partial g_k}{\partial t}(t, X)\mathrm{d}t + \sum_{i=1}^n \frac{\partial g_k}{\partial x_i}(t, X)\mathrm{d}X_i + \frac{1}{2}\sum_{i,j=1}^n \frac{\partial^2 g_k}{\partial x_i \partial x_j}(t, X)\mathrm{d}X_i\mathrm{d}X_j \ ,$$

where the following "multiplication table" holds

$$\mathrm{d}t.\mathrm{d}t = \mathrm{d}t.\mathrm{d}B_i = \mathrm{d}B_i.\mathrm{d}t = 0$$
, $\mathrm{d}B_i.\mathrm{d}B_j = \delta_{ij}\mathrm{d}t$.

• The proof is analogous to the 1-dimensional version.

A - A - B

Example

Let $B = (B_1, ..., B_n)$ be a Brownian motion in \mathbb{R}^n and $n \ge 2$. Consider the stochastic process given by

$$R(t,\omega) = |B(t,\omega)| = \left(B_1^2(t,\omega) + \cdots + B_n^2(t,\omega)
ight)^{1/2} \; ,$$

i.e. the distance to the origin to the Brownian motion B. Although g(t,x) = |x| is not a C^2 function at the origin, Itô's formula still holds since B never hits the origin a.s. when $n \ge 2$. We get

$$\mathrm{d}R = \sum_{i=1}^{n} \frac{B_i}{R} \mathrm{d}B_i + \frac{n-1}{2R} \mathrm{d}t \; .$$

The process R above is called the *n*-dimensional Bessel process.

・ロト ・回ト ・ヨト ・ヨ